**Date:** 25/10/2019

**Not In Attendance:** Kieran, Ibraheem

**What’s Been Done since the Previous Meeting:**

**Kieran:** N/A

**Ibraheem:** N/A

**Taylor:** Reading on Code of Ethics; Principles of Computing. Further research into the ethics behind autonomous vehicles. Key point – autonomous vehicles should seek to take the path which minimizes damage as much as possible if such an option is available, instead of choosing one life over another. Also contributed to Basecamp setup/planning.

**James:** Contributed to Basecamp setup and planning; scheduled meetings for the week.

**What’s Being Done:**

**Kieran:** Working towards completing the planning stage.

**Ibraheem:** Working towards completing the planning stage.

**Taylor:** Working towards completing the planning stage.

**James:** Working towards completing the planning stage.

**Further Discussion:**

Could the user’s opinion of autonomous vehicles be gathered? For/against/neutral, etc? Something to ask in meeting with supervisor. Should the ethics generator focus on just a life/death scenario or should it also consider the possibly of injury? Discussed whether ‘minimizing damage’ falls under prioritizing one life based on different factors.

Discussed potential of gathering further information from users.

In the case of our project, it will be assumed that the vehicle will have complete control without input from the user.

Further discussed ideas for first person and third person perspectives, and also time limits. Basic functionality of program has been discussed, as well as whether or not it should branch out to different types of vehicles/transport methods, thus bringing in the possibility of different scenarios.

**James’ Notes:**

1. Start with autonomous, then vary in scope.

2. Do in python and use IntelliJ

3. Github will be the respository

4. Using Basecamp as the project driver

5. Having a tree based of users decisions

6. Timer will be present on decision

7. Keep one tree as automated cars

8. Meeting twice a week Thurs and Fri?